## ECE 321C Electronic Circuits

Lec. 8: BJT Low Frequency Response

Instructor

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## Agenda

Low Frequency Analysis- Bode Plot

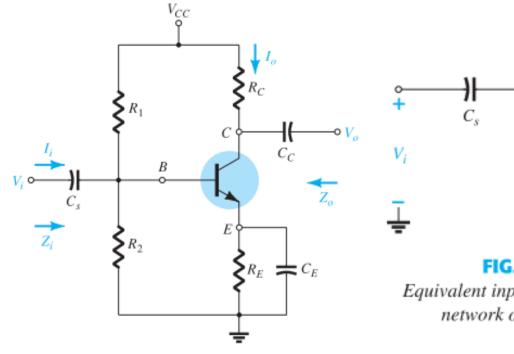
Low Frequency Response – BJT Amplifier with R

Impact of R<sub>s</sub> on the BJT Low Frequency Response

## Low Frequency Analysis- Bode Plot

## Defining the Low Cutoff Frequency

- In the low-frequency region of the single-stage BJT amplifier, it is the RC combinations formed by the network capacitors C<sub>C</sub>, C<sub>E</sub>, and C<sub>s</sub> and the network resistive parameters that determine the cutoff frequencies
- Voltage-Divider Bias Config.



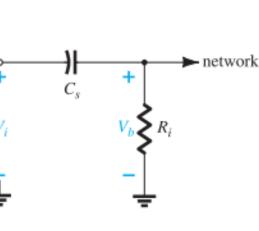
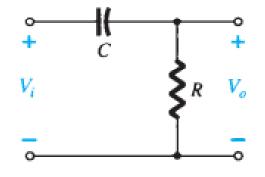


FIG. 9.16 Equivalent input circuit for the network of Fig. 9.15.



#### FIG. 9.14

RC combination that will define a low-cutoff frequency.

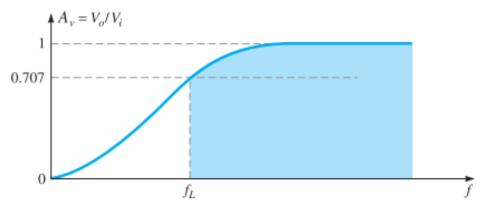
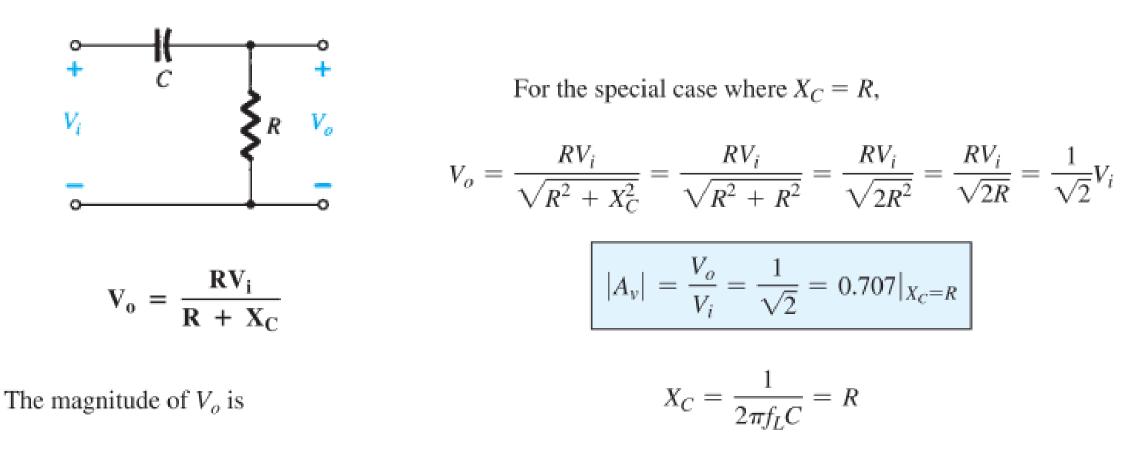


FIG. 9.19 Low-frequency response for the RC circuit of Fig. 9.14.

FIG. 9.15 Voltage-divider bias configuration.

 $Z_i = R_i = R_1 \|R_2\|\beta r_e$ 

Defining The Low Cutoff Frequency ..



 $f_L = \frac{1}{2\pi RC}$ 

$$V_o = \frac{RV_i}{\sqrt{R^2 + X_C^2}}$$

Defining The Low Cutoff Frequency ..

$$A_{v} = \frac{V_{o}}{V_{i}} = \frac{R}{R - jX_{C}} = \frac{1}{1 - j(X_{C}/R)} = \frac{1}{1 - j(1/\omega CR)} = \frac{1}{1 - j(1/2\pi fCR)}$$
$$A_{v} = \frac{1}{1 - j(f_{L}/f)}$$

In the magnitude and phase form,

$$A_{\nu} = \frac{V_o}{V_i} = \frac{1}{\underbrace{\sqrt{1 + (f_L/f)^2}}_{\text{magnitude of } A_{\nu}}} \underbrace{/ \tan^{-1}(f_L/f)}_{\text{phase} \measuredangle by \text{ which}}}$$

$$A_{\nu(\text{dB})} = 20 \log_{10} \frac{1}{\sqrt{1 + (f_L/f)^2}}$$

$$\theta = \tan^{-1} \frac{f_L}{f}$$

when  $f = f_L$ ,

$$|A_v| = \frac{1}{\sqrt{1 + (1)^2}} = \frac{1}{\sqrt{2}} = 0.707 \Longrightarrow -3 \,\mathrm{dB}$$

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## Bode Plot

$$A_{\nu(dB)} = 20 \log_{10} \frac{1}{\sqrt{1 + (f_L/f)^2}}$$
$$A_{\nu(dB)} = -20 \log_{10} \left[ 1 + \left(\frac{f_L}{f}\right)^2 \right]^{1/2}$$
$$= -\left(\frac{1}{2}\right)(20) \log_{10} \left[ 1 + \left(\frac{f_L}{f}\right)^2 \right]$$
$$= -10 \log_{10} \left[ 1 + \left(\frac{f_L}{f}\right)^2 \right]$$

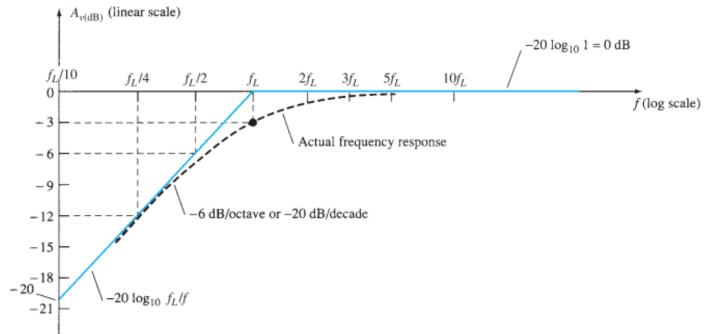
For frequencies where  $f \ll f_L$  or  $(f_L/f)^2 \gg 1$ ,

$$A_{\nu(dB)} = -10 \log_{10} \left(\frac{f_L}{f}\right)^2$$
$$A_{\nu(dB)} = -20 \log_{10} \frac{f_L}{f}$$
$$f \ll f_L$$

## Bode Plot

$$A_{\nu(\mathrm{dB})} = -20\log_{10}\frac{f_L}{f}$$

• The piecewise linear plot of the asymptotes and associated breakpoints is called a Bode plot of the magnitude versus frequency.



- A change in frequency by a factor of two, equivalent to one octave, results in a 6-dB change in the ratio, as shown by the change in gain from f<sub>L</sub>/2 to f<sub>L</sub>.
- For a 10:1 change in frequency, equivalent to one decade, there is a 20-dB change in the ratio, as demonstrated between the frequencies of  $f_L/10$  and  $f_L$ .

## Bode Plot..

Phase Angle:

$$\theta = \tan^{-1} \frac{f_L}{f}$$

For frequencies  $f \ll f_L$ ,  $\theta = \tan^{-1} \frac{f_L}{f} \rightarrow 90^\circ$  $V_o$  leads  $V_i$ For instance, if  $f_L = 100f$ , 90°  $\theta = \tan^{-1} \frac{f_L}{f} = \tan^{-1}(100) = 89.4^{\circ}$ For  $f = f_L$ , 45°  $\theta = \tan^{-1} \frac{f_L}{f} = \tan^{-1} 1 = 45^\circ$ 0° For  $f \gg f_L$ ,  $2f_L$  $3f_L$  $0.2f_L = 0.3f_L = 0.5f_L$  $0.1f_L$  $f_L$  $5f_L$  $10f_L$  $\theta = \tan^{-1} \frac{f_L}{f} \rightarrow 0^\circ$ FIG. 9.22

Phase response for the RC circuit of Fig. 9.14.

For instance, if  $f = 100 f_L$ ,

$$\theta = \tan^{-1} \frac{f_L}{f} = \tan^{-1} 0.01 = 0.573^{\circ}$$

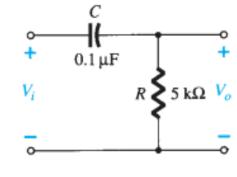
### Example

#### **EXAMPLE 9.10** For the network of Fig. 9.23:

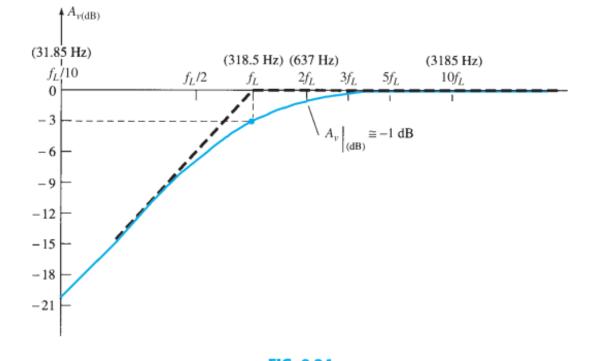
- a. Determine the break frequency.
- b. Sketch the asymptotes and locate the -3-dB point.
- c. Sketch the frequency response curve.
- d. Find the gain at  $A_{v(dB)} = -6 \text{ dB}$ .

#### Solution:

a. 
$$f_L = \frac{1}{2\pi RC} = \frac{1}{(6.28)(5 \times 10^3 \ \Omega)(0.1 \times 10^{-6} \ \text{F})}$$
  
 $\cong$  **318.5 Hz**  
b. and c. See Fig. 9.24.  
d. Eq. (9.27):  $A_v = \frac{V_o}{V_i} = 10^{A_{v(\text{dB})/20}}$   
 $= 10^{(-6/20)} = 10^{-0.3} = 0.501$   
and  $V_o = 0.501 \ V_i$  or approximately 50% of  $V_i$ .







# Low Frequency Response – BJT Amplifier with $R_L$

## Loaded BJT Amplifier

In the voltage-divider ct.

 $\rightarrow$  the capacitors Cs, C<sub>c</sub>, and C<sub>E</sub> will determine the low-frequency response.

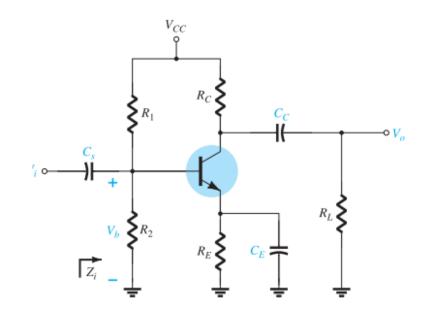
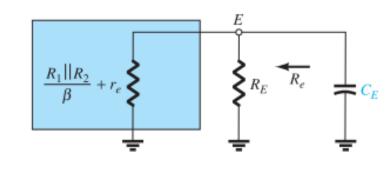
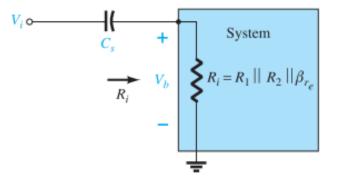
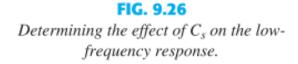


FIG. 9.25 Loaded BJT amplifier with capacitors that affect the lowfrequency response.



**FIG. 9.30** Localized ac equivalent of  $C_E$ .





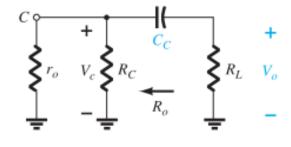
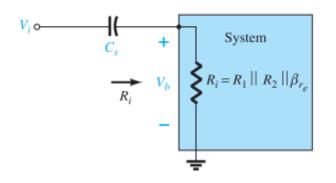


FIG. 9.28 Localized ac equivalent for  $C_C$  with  $V_i = 0 V$ .

 $f_L = \max(f_{Ls}, f_{Lc}, f_{LE})$ 

## Loaded BJT Amplifier





**FIG. 9.26** Determining the effect of  $C_s$  on the lowfrequency response.



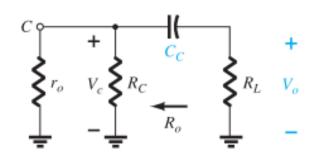


FIG. 9.28 Localized ac equivalent for  $C_C$  with  $V_i = 0 V$ .

$$R_i = R_1 \| R_2 \| \beta r_e.$$

$$f_{L_s} = \frac{1}{2\pi R_i C_s}$$

$$f_{L_C} = \frac{1}{2\pi (R_o + R_L)C_C}$$

 $R_o = R_C \| r_o$ 

 $\rightarrow C_{E}$ :

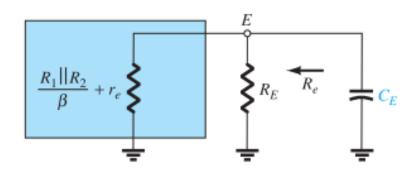


FIG. 9.30 Localized ac equivalent of  $C_E$ .

$$R_e = R_E \| \left( \frac{R_1 \| R_2}{\beta} + r_e \right) \|$$

$$f_{L_E} = \frac{1}{2\pi R_e C_E}$$

 $f_L = \max(f_{Ls}, f_{Lc}, f_{LE})$ 

# Impact of $R_s$ on the BJT Low Frequency Response

## Impact of $R_S$

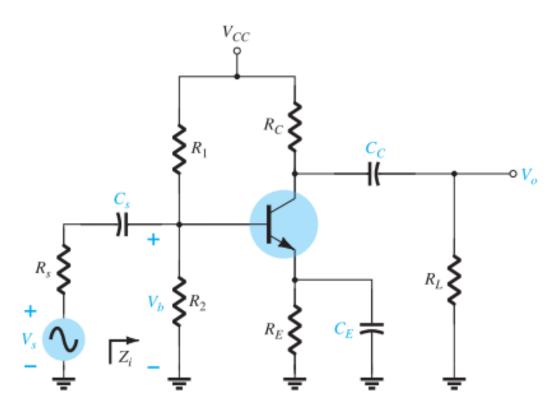
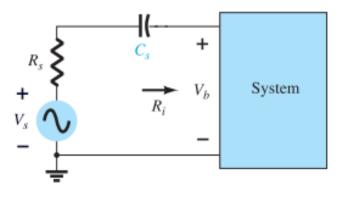


FIG. 9.32 Determining the effect of  $R_s$  on the low-frequency response of a BJT amplifier.



#### FIG. 9.33 Determining the effect of C<sub>s</sub> on the lowfrequency response.

$$f_{L_s} = \frac{1}{2\pi (R_i + R_s)C_s}$$

$$f_{L_C} = \frac{1}{2\pi (R_o + R_L)C_C}$$

$$f_{L_E} = \frac{1}{2\pi R_e C_E}$$

$$R_e = R_E \left\| \left( \frac{R'_s}{\beta} + r_e \right) \text{ and } R'_s = R_s \left\| R_1 \right\| R_2$$

